

# On the Smallest Enclosing Information Disk

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# Smallest Enclosing Balls

## Problem

Given  $\mathcal{S} = \{\mathbf{s}_1, \dots, \mathbf{s}_n\}$ , compute a simplified description, called the **center**, that fits well  $\mathcal{S}$  (i.e., summarizes  $\mathcal{S}$ ).

Two optimization criteria:

**MINAVG** Find a center  $\mathbf{c}^*$  which minimizes the *average distortion* w.r.t  $\mathcal{S}$ :  $\mathbf{c}^* = \operatorname{argmin}_{\mathbf{c}} \sum_i d(\mathbf{c}, \mathbf{s}_i)$ .

**MINMAX** Find a center  $\mathbf{c}^*$  which minimizes the *maximal distortion* w.r.t  $\mathcal{S}$ :  $\mathbf{c}^* = \operatorname{argmin}_{\mathbf{c}} \max_i d(\mathbf{c}, \mathbf{s}_i)$ .

Investigated in Applied Mathematics:

- Computational geometry ( $1$ -center problem),
- Computational statistics ( $1$ -point estimator),
- Machine learning ( $1$ -class classification),

# Smallest Enclosing Balls in Computational Geometry

Distortion measure  $d(\cdot, \cdot)$  is the **geometric distance**:

Euclidean distance  $L_2$ .

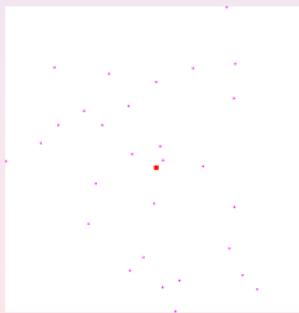
$\mathbf{c}^*$  is the **circumcenter** of  $\mathcal{S}$  for MINMAX,

Squared Euclidean distance  $L_2^2$ .

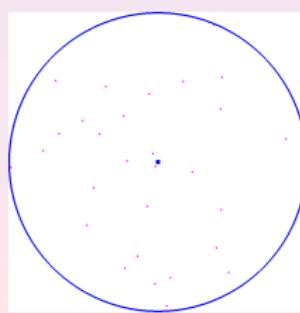
$\mathbf{c}^*$  is the **centroid** of  $\mathcal{S}$  for MINAVG ( $\rightarrow k$ -means),

Euclidean distance  $L_2$ .

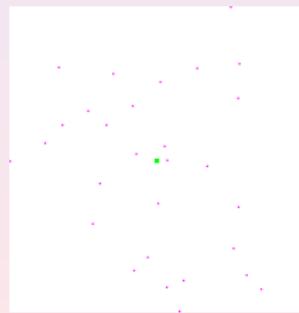
$\mathbf{c}^*$  is the **Fermat-Weber** point for MINAVG.



Centroid  
MINAVG  $L_2^2$



Circumcenter  
MINMAX  $L_2$

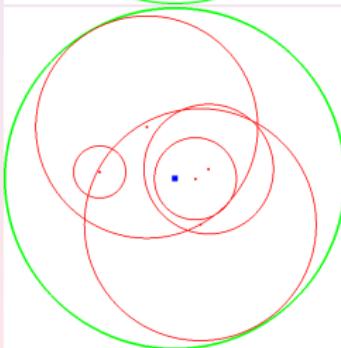
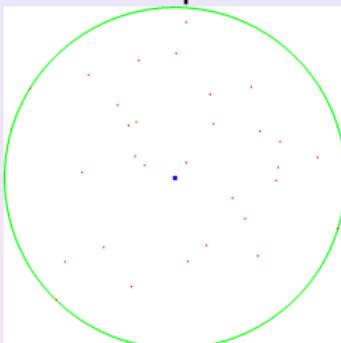


Fermat-Weber  
MINAVG  $L_2$

## Smallest Enclosing Ball [NN'04]

- Pioneered by Sylvester (1857),
- Unique circumcenter  $\mathbf{c}^*$  (radius  $r^*$ ),
- LP-type, linear-time randomized algorithm (fixed dimension  $d$ ),
- Weakly polynomial.
- Efficient SOCP numerical solver,
- Fast combinatorial heuristics ( $d \geq 1000$ ).

MINMAX point set



MINMAX ball set

# Distortions: Bregman Divergences

## Definition

Bregman divergences are parameterized ( $F$ ) families of distortions.

Let  $F : \mathcal{X} \rightarrow \mathbb{R}$ , such that  $F$  is *strictly convex* and *differentiable* on  $\text{int}(\mathcal{X})$ , for a convex domain  $\mathcal{X} \subseteq \mathbb{R}^d$ .

Bregman divergence  $D_F$ :

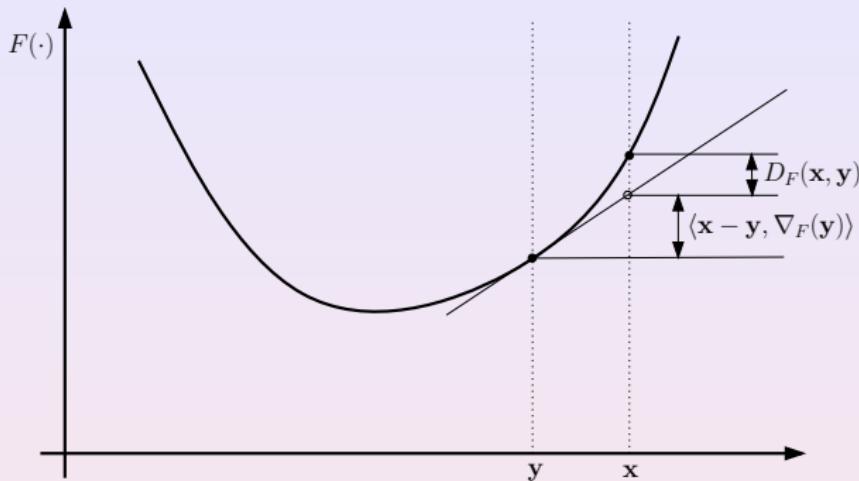
$$D_F(\mathbf{x}, \mathbf{y}) = F(\mathbf{x}) - F(\mathbf{y}) - \langle \mathbf{x} - \mathbf{y}, \nabla F(\mathbf{y}) \rangle .$$

$\nabla F$  : gradient operator of  $F$

$\langle \cdot, \cdot \rangle$  : Inner product (dot product)

( $\rightarrow D_F$  is the tail of a Taylor expansion of  $F$ )

# Visualizing $F$ and $D_F$



$$D_F(\mathbf{x}, \mathbf{y}) = F(\mathbf{x}) - F(\mathbf{y}) - \langle \mathbf{x} - \mathbf{y}, \nabla F(\mathbf{y}) \rangle .$$

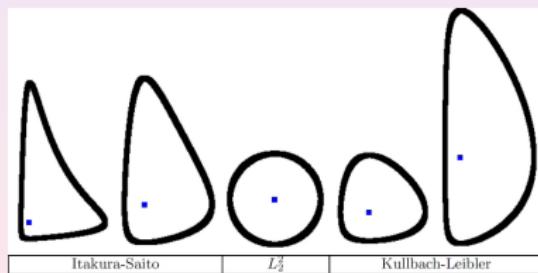
( $\rightarrow D_F$  is the a truncated Taylor expansion of  $F$ )

# Bregman Balls (Information Balls)

- Euclidean Ball:  $\mathcal{B}_{\mathbf{c},r} = \{\mathbf{x} \in \mathcal{X} : \|\mathbf{x} - \mathbf{c}\|_2^2 \leq r\}$   
( $r$ : squared radius.  $L_2^2$ : Bregman divergence  $F(\mathbf{x}) = \sum_{i=1}^d x_i^2$ )

Theorem [BMDG'04]

The MINAvg Ball for Bregman divergences is the **centroid**.



# Two types of Bregman balls

- First-type:

$$\mathcal{B}_{\mathbf{c},r} = \{\mathbf{x} \in \mathcal{X} : D_F(\boxed{\mathbf{c}}, \mathbf{x}) \leq r\},$$

- Second-type:

$$\mathcal{B}'_{\mathbf{c},r} = \{\mathbf{x} \in \mathcal{X} : D_F(\mathbf{x}, \boxed{\mathbf{c}}) \leq r\}$$

## Lemma

The smallest enclosing Bregman balls  $\mathcal{B}_{\mathbf{c}^*,r^*}$  and  $\mathcal{B}'_{\mathbf{c}^*,r^*}$  of  $\mathcal{S}$  are unique.

→ Consider first-type Bregman balls.

(The second-type is obtained as a first-type ball on the dual divergence  $D_{F^*}$  using the Legendre-Fenchel transformation.)

# Applications of Bregman Balls

Circumcenters of the smallest enclosing Bregman balls encode:  
Euclidean squared distance.

The closest point to a set of points.

$$D_F(\mathbf{p}, \mathbf{q}) = \sum_{i=1}^d (q_i - p_i)^2 = \|\mathbf{p}\|^2 + \|\mathbf{q}\|^2 - 2\langle \mathbf{p}, \mathbf{q} \rangle.$$

Itakura-Saito divergence. The closest (sound) signal to a set of signals (speech recognition).

$$D_F(\mathbf{p}, \mathbf{q}) = \sum_{i=1}^d \left( \frac{p_i}{q_i} - \log \frac{p_i}{q_i} - 1 \right), [\leftarrow F(\mathbf{x}) = - \sum_{i=1}^d \log x_i]$$

Kullback-Leibler. The closest distribution to a set of distributions (density estimation).

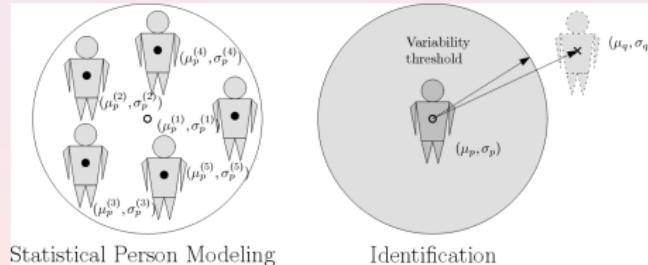
$$D_F(\mathbf{p}, \mathbf{q}) = \sum_{i=1}^d p_i \log \frac{p_i}{q_i} - p_i + q_i, [F(\mathbf{x}) = - \sum_{i=1}^d x_i \log x_i]$$

# Information Disks

## Problem

Given a set  $\mathcal{S} = \{\mathbf{s}_1, \dots, \mathbf{s}_n\}$  of  $n$  2D vector points, compute the MINMAX center:  $\mathbf{c}^* = \operatorname{argmin}_{\mathbf{c}} \max_i d(\mathbf{c}, \mathbf{s}_i)$ .

- handle geometric points for various distortions,
- handle parametric distributions  
(e.g., Normal distributions are parameterized by  $(\mu, \sigma)$ ).



# Information Disk is LP-type

Monotonicity. For any  $\mathcal{F}$  and  $\mathcal{G}$  such that  $\mathcal{F} \subseteq \mathcal{G} \subseteq \mathcal{X}$ ,

$$r^*(\mathcal{F}) \leq r^*(\mathcal{G}).$$

Locality. For any  $\mathcal{F}$  and  $\mathcal{G}$  such that  $\mathcal{F} \subseteq \mathcal{G} \subseteq \mathcal{X}$  with

$$r^*(\mathcal{F}) = r^*(\mathcal{G}), \text{ and any point } \mathbf{p} \in \mathcal{X},$$

$$r^*(\mathcal{G}) < r^*(\mathcal{G} \cup \{\mathbf{p}\}) \rightarrow r^*(\mathcal{F}) < r^*(\mathcal{F} \cup \{\mathbf{p}\}).$$

**MININFOBALL**( $\mathcal{S} = \{\mathbf{p}_1, \dots, \mathbf{p}_n\}, \mathcal{B}$ ):

◁ Initially  $\mathcal{B} = \emptyset$ . Returns  $B^* = (\mathbf{c}^*, r^*)$  ▷

**IF**  $|\mathcal{S} \cup \mathcal{B}| \leq 3$

**RETURN**  $B = \text{SOLVEINFOBASIS}(\mathcal{S} \cup \mathcal{B})$

**ELSE**

◁ Select at random  $\mathbf{p} \in \mathcal{S}$  ▷

$B^* = \text{MININFOBALL}(\mathcal{S} \setminus \{\mathbf{p}\}, \mathcal{B})$

**IF**  $\mathbf{p} \notin B^*$

◁ Then add  $\mathbf{p}$  to the basis ▷

$\text{MININFOBALL}(\mathcal{S} \setminus \{\mathbf{p}\}, \mathcal{B} \cup \{\mathbf{p}\})$

# Computing basis (SOLVEINFOBASIS)

## Lemma

The first-type Bregman bisector

$\text{Bisector}(\mathbf{p}, \mathbf{q}) = \{\mathbf{c} \in \mathcal{X} \mid D_F(\mathbf{c}, \mathbf{p}) = D_F(\mathbf{c}, \mathbf{q})\}$  is linear.

This is a linear equation in  $\mathbf{c}$  (an *hyperplane*). Bisector

$\text{Bisector}(\mathbf{p}, \mathbf{q}) = \{\mathbf{x} \mid \langle \mathbf{x}, \mathbf{d}_{\mathbf{pq}} \rangle + k_{\mathbf{pq}} = 0\}$  with

- $\mathbf{d}_{\mathbf{pq}} = \nabla F(\mathbf{p}) - \nabla F(\mathbf{q})$  a vector, and
- $k_{\mathbf{pq}} = F(\mathbf{p}) - F(\mathbf{q}) + \langle \mathbf{q}, \nabla F(\mathbf{q}) \rangle - \langle \mathbf{p}, \nabla F(\mathbf{p}) \rangle$  a constant



(Itakura-Saito divergence)

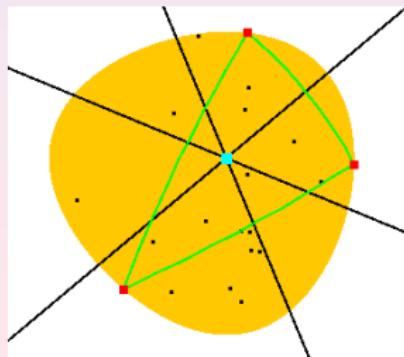
# Computing basis (SOLVEINFOBASIS)

**Basis 3**: The circumcenter is the trisector.

(intersection of 3 linear bisectors, enough to consider any two of them).

$$\mathbf{c}^* = \mathbf{l}_{12} \times \mathbf{l}_{13} = \mathbf{l}_{12} \times \mathbf{l}_{23} = \mathbf{l}_{13} \times \mathbf{l}_{23},$$

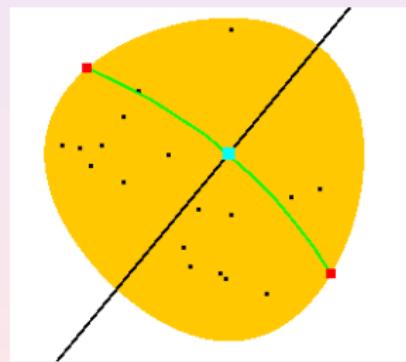
$\mathbf{l}_{ij}$ : projective point associated to the linear bisector  
Bisector( $\mathbf{p}_i, \mathbf{p}_j$ ) ( $\times$ : cross-product)



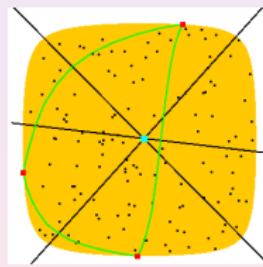
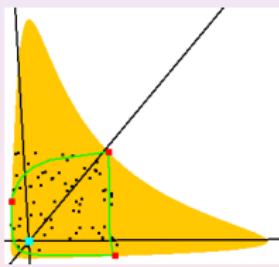
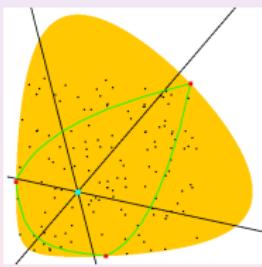
# Computing basis (SOLVEINFOBASIS)

**Basis 2**: Either minimize  $D_F(\mathbf{c}, \mathbf{p})$  s.t.  $\mathbf{c}^* \in \text{Bisector}(\mathbf{p}, \mathbf{q})$ , or better perform a logarithmic search on  $\lambda \in [0, 1]$  s. t.

$\mathbf{r}_\lambda = \nabla F^{-1}((1 - \lambda)\nabla F(\mathbf{p}) + \lambda\nabla F(\mathbf{q}))$  is on the geodesic of  $\mathbf{pq}$  ( $\nabla F^{-1}$ : reciprocal gradient).



[http://www.cs.l.sony.co.jp/person/nielsen/  
BregmanBall/MINIBALL/](http://www.cs.l.sony.co.jp/person/nielsen/BregmanBall/MINIBALL/)



# Statistical application example

Univariate Normal law distribution:

$$N(x|\mu, \sigma) = \frac{1}{\sigma\sqrt{2\pi}} \exp\left(-\frac{(x-\mu)^2}{2\sigma^2}\right).$$

Consider the Kullback-Leibler divergence of two distributions:

$$\text{KL}(f, g) = \int_x f(x) \log \frac{f(x)}{g(x)}.$$

Canonical form of an *exponential family*:

$$N(x|\mu, \sigma) = \frac{1}{\sqrt{2\pi}Z(\theta)} \exp\{\langle \theta, \mathbf{f}(x) \rangle\} \text{ with:}$$

- $Z(\theta) = \sigma \exp\left\{\frac{\mu^2}{2\sigma^2}\right\} = \sqrt{-\frac{1}{2\theta_1}} \exp\left\{-\frac{\theta_2^2}{4\theta_1}\right\},$
- $\mathbf{f}(x) = [x^2 \ x]^T$ : *sufficient statistics*,
- $\theta = [-\frac{1}{2\sigma^2} \ \frac{\mu}{\sigma^2}]^T$ : *natural parameters*.

Kullback-Leibler of parametric exponential family is a Bregman divergence for  $F = \log Z$ .

$$\text{KL}(\theta_p || \theta_q) = D_F(\theta_p, \theta_q) = \langle (\theta_p - \theta_q), \theta_p[\mathbf{f}] \rangle + \log \frac{Z(\theta_q)}{Z(\theta_p)}$$

$$\theta_p[\mathbf{f}] = \begin{bmatrix} \int_X \frac{x^2}{Z(\theta_p)} \exp\{\langle \theta_p, \mathbf{f}(x) \rangle\} \\ \int_X \frac{x}{Z(\theta_p)} \exp\{\langle \theta_p, \mathbf{f}(x) \rangle\} \end{bmatrix} = \begin{bmatrix} \mu_p^2 + \sigma_p^2 \\ \mu_p \end{bmatrix}$$

$$\text{Bisection } \langle (\theta_p - \theta_q), \theta_c[\mathbf{f}] \rangle + \log \frac{Z(\theta_p)}{Z(\theta_q)} = 0.$$

## 1D Gaussian distribution: change variables

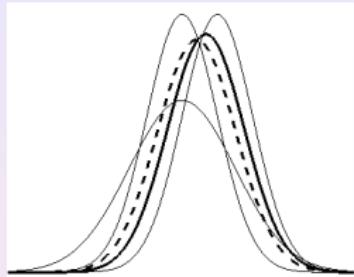
$$(\mu, \sigma) \rightarrow (\mu^2 + \sigma^2, \mu) = (x, y) \text{ (with } x > y > 0).$$

$$\text{It comes } Z(x, y) = \sqrt{x - y^2} \exp\left\{\frac{y^2}{2(x-y^2)}\right\},$$

$$\log Z(x, y) = \log \sqrt{x - y^2} + \frac{y^2}{2(x-y^2)} \text{ and}$$

$$\nabla F(x, y) = \left( \frac{1}{2(x-y^2)} - \frac{y^2}{2(x-y^2)}, \frac{y^3}{(x-y^2)^2} \right).$$

# Statistical application example (cont'd)



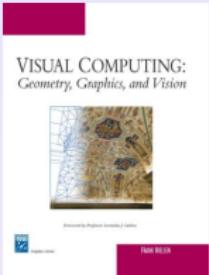
- MINMAX:  $(\mu^*, \sigma^*) \simeq (2.67446, 1.08313)$  and

$$r^* \simeq 0.801357,$$



- MINAVG:  $(\mu^{*\prime}, \sigma^{*\prime}) = (2.40909, 1.10782)$ .

Note that  $\text{KL}(N_i, N_j) = \frac{1}{2} \left( \frac{\sigma_i^2}{\sigma_j^2} + 2 \log \frac{\sigma_j}{\sigma_i} - 1 + \frac{(\mu_j - \mu_i)^2}{\sigma_j^2} \right)$ .



- Java Applet online:

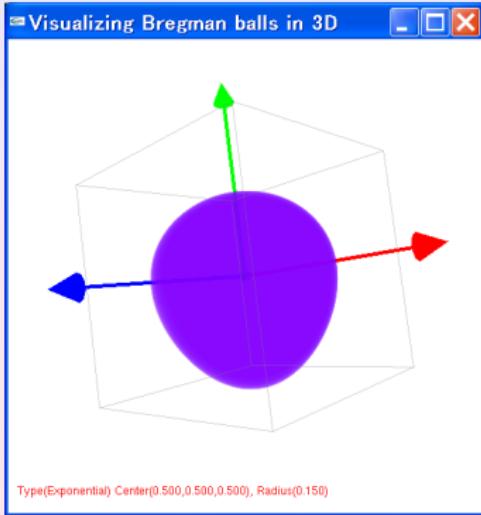
[www.cs1.sony.co.jp/person/nielsen/BregmanBall/  
MINIBALL/](http://www.cs1.sony.co.jp/person/nielsen/BregmanBall/MINIBALL/)

- Source code: Basic MiniBall, Line intersection by projective geometry

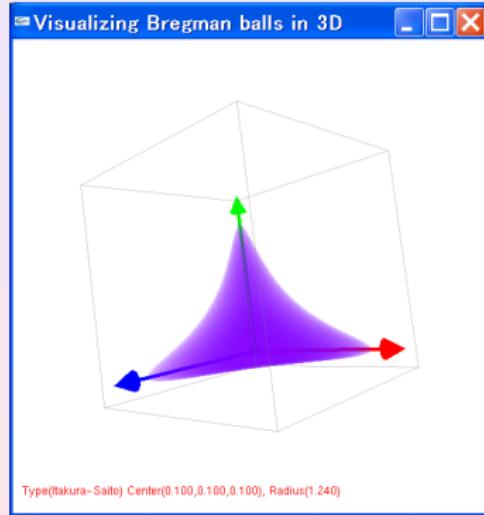
*Visual Computing: Geometry, Graphics, and Vision*, ISBN 1-58450-427-7, 2005.

- In high dimensions, extend Bădoiu & Clarkson core-set  
See *On approximating the smallest enclosing Bregman Balls* (SoCG'06 video)

# 3D Bregman balls (video)

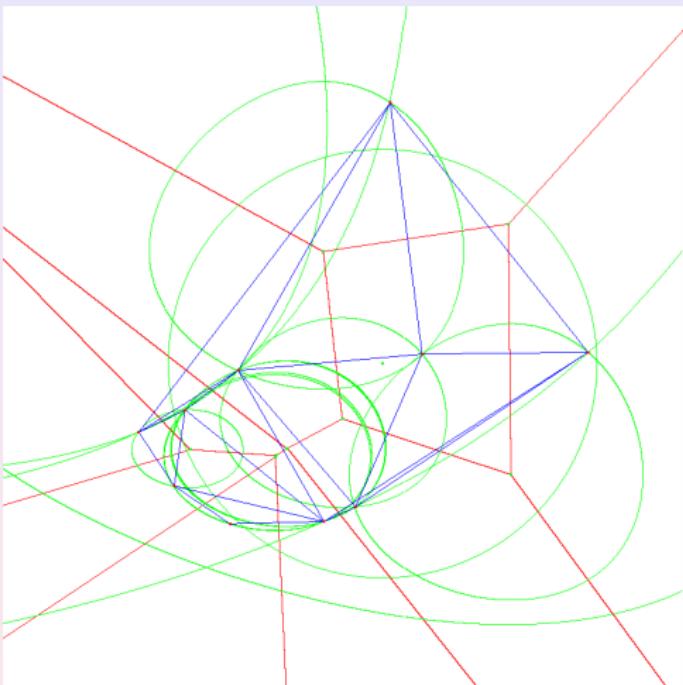


Relative entropy (KL)



Itakura-Saito

# Bregman Voronoi/Delaunay



# Bibliography

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- Crammer & Singer, "Learning Algorithms for Enclosing Points in Bregmanian Spheres", COLT03.
- Nock & Nielsen, "Fitting the smallest Bregman ball", ECML05 (SoCG06 video).
- Banerjee et. al, "Clustering with Bregman divergences" , JMLR05.